In conclusion, we will present some of the dimensional quantities corresponding to plate motion with Re\* =  $3 \cdot 10^3$  in an electrolyte with  $\sigma = 10^{12}$  l/sec. Let  $2\alpha = 10^2$  cm. Then from Eq. (2.6) at  $\delta = 0.4$  it follows that  $\omega = 9 \cdot 10^4$  l/sec, and from Eq. (4.4) and  $v_0/u_0 = 0.39$  we have  $v_0 = 1.2^{\circ}10^{-1}$  cm/sec; from Eq. (4.3), (2.5) we determine the amplitude of the maximum magnetic field intensity  $H_0 = 2\pi I_0/\sec \simeq 2.7$  G.

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## UNSTEADY FLOW OF A NON-NEWTONIAN LIQUID WITH A POWER RHEOLOGICAL LAW PAST A FLAT PENETRABLE PLATE

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We analyze the problem of the unsteady flow of a non-Newtonian liquid with a power rheological law past a flat penetrable plate. In contrast with [1], where a similarly posed problem is treated for a pseudoplastic liquid, we solve the problem for a dilatant liquid.

For a non-Newtonian liquid with a power rheological law, the relation between the shear stress  $\tau$  and the velocity gradient  $\partial u/\partial z$  for plane motion has the form [2]

$$\tau = k \left| \frac{\partial u}{\partial z} \right|^{n-1} \frac{\partial u}{\partial z} \quad (n > 0),$$

where k and n are rheological constants of the medium; the case n = 1 corresponds to Newtonian liquid, n < 1 to a pseudoplastic liquid, and n > 1 to a dilatant liquid.

The problem of the flow of a non-Newtonian liquid with a power rheological law past an infinite flat plate in the presence of uniform suction of liquid depending on time according to a definite law was treated in [1]. This problem was solved for pseudoplastic (n < 1) and Newtonian (n = 1) liquids. We solve the problem in a similar formulation without restriction on the possible values of n > 0.

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We consider the unsteady flow of a power-law liquid past a flat surface z = 0 (Fig. 1) across which there is a transverse motion of liquid with the velocity

$$v(t) = \frac{\beta}{n+1} \left( \frac{U_{\infty}^{1-n}}{na} \right)^{-\frac{1}{n+1}} (t+t_0)^{-\frac{n}{n+1}},$$
(1)

where  $\beta$  = const is the velocity of the incoming flow; t, time; to, initial time; and  $a = k/\rho$ .

In the boundary-layer theory approximation the equation of the nongradient motion of a power-law liquid can be written in the form

$$\frac{\partial u}{\partial t} + v(t)\frac{\partial u}{\partial z} = a\frac{\partial}{\partial z} \left(\frac{\partial u}{\partial z}\right)^n.$$
(2)

The problem of the existence and general character of the behavior of the solution of an equation of the type (2) is covered in detail in [3, 4].

An exact analytic solution of Eq. (2) for an arbitrary law of motion of the liquid v(t) has not been obtained, but an exact self-similar solution of Eq. (1) exists.

The boundary conditions in the case under consideration are

$$u(0) = 0, u(\infty) = U_{\infty}. \tag{3}$$

The self-similar variable  $\eta$  and the velocity u are written in the form

$$\eta = \left(\frac{U_{\infty}^{1-n}}{na}\right)^{\frac{1}{n+1}} (t+t_0)^{-\frac{1}{n+1}} z, \quad u = U_{\infty} f(\eta).$$
(4)

By using (1) and (4) the solution of (2) and (3) can be reduced to the integration of the ordinary differential equation

$$\frac{n-1}{n+1}(\beta-\eta) = \frac{d}{d\eta} \left(\frac{dj}{d\eta}\right)^{n-1}$$
(5)

with the boundary conditions

$$f(0) = 0, f(\infty) = 1.$$
 (6)

Integrating (5) twice, we obtain

$$f(\eta) = \left[\frac{n-1}{2(n+1)}\right]^{\frac{1}{n-1}} \int_{0}^{\eta} (2\beta\eta - \eta^{2} + \text{const})^{\frac{1}{n-1}} d\eta.$$
(7)

The solution of Eq. (5) is essentially different for n < 1 and n > 1, and therefore we treat these cases separately.

For n < 1 it is convenient to rewrite Eq. (7) in the form

$$f(\eta) = \left[\frac{1-n}{2(1+n)}\right]^{\frac{1}{n-1}} \int_{0}^{\eta} \left[(\eta-\beta)^{2} + A^{2}\right]^{\frac{1}{n-1}} d\eta$$

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where A is a constant to be determined.

By introducing the new variables  $\xi = \eta - \beta$ , and using boundary condition (6), we obtain

$$\int_{-\beta}^{\infty} \left(\xi^2 + A^2\right)^{\frac{1}{n-1}} d\xi = \left[\frac{2\left(1+n\right)}{1-n}\right]^{\frac{1}{n-1}}.$$
(8)

Evaluating the integral on the left-hand side of (8), we obtain a transcendental equation for the constant A

$$\frac{\frac{1}{2}A^{\frac{n+1}{n-1}}B\left[\frac{1}{2},\frac{n+1}{2(1-n)}\right] + \frac{1}{2}A^{\frac{2}{n-1}}\beta B\left(1,\frac{1}{2}\right)F\left(-\frac{1}{n-1},\frac{1}{2},\frac{3}{2},-\frac{\beta^2}{A^2}\right) \\ = \left[\frac{2(1+n)}{1-n}\right]^{\frac{1}{n-1}},$$

where B (p, q) is the beta function and F ( $\alpha$ ,  $\beta$ ,  $\gamma$ , z) is the hypergeometric function. For n > 1 we have

$$f(\eta) = \left[\frac{(n-1)}{2(n+1)}\right]^{\frac{1}{n-1}} \int_{0}^{\eta} \left[C^{2} - (\eta - \beta)^{2}\right]^{\frac{1}{n-1}} d\eta, \qquad (9)$$

where C is a constant to be determined.

Study of (9) shows that a limiting value  $n = n_f$  exists such that for all  $n > n_f f(n) = 1$ , i.e., shear perturbations for n > 1 are localized within a finite distance from the surface of the plate.

By introducing the new variable

$$(y-\beta)^2=C^2,$$

we obtain two supplementary conditions:

$$f(\eta) = 1, df/d\eta|_{\eta=y} = 0.$$
 (10)

Taking account of (10), we have

$$\int_{0}^{y} \left[ (y-\beta)^{2} - (\eta-\beta)^{2} \right]^{\frac{1}{n-1}} d\eta = \left[ \frac{2(n+1)}{n-1} \right]^{\frac{1}{n-1}}$$
(11)

Introducing the variables  $\theta = \eta - \beta$  and  $v = z - \beta$ , and evaluating the integral in (11), we find an equation for C

$$y^{\frac{n+1}{n-1}}\left[\frac{1}{2}B\left(\frac{1}{2},\frac{n}{n+1}\right)+2^{\frac{n+1}{n-1}}\left\{B_{\frac{y+\beta}{y}}\left(\frac{n}{n-1},\frac{n}{n-1}\right)-B_{\frac{1}{2}}\left(\frac{n}{n-1},\frac{n}{n-1}\right)\right\}\right]=\left[\frac{2(n+1)}{n-1}\right]^{\frac{1}{n-1}},$$

where  $B_p(p, q)$  is the incomplete beta function.

Results calculated with the equations derived are shown in Figs. 2 and 3. Figure 2 shows dimensionless velocity profiles for various values of n and the injection parameter (suction)  $\beta$  [1) n = 2; 2) 1.25; 3) 0.5]. Figure 3 shows the position of the front of the shear perturbations as a function of the injection parameter (suction)  $\beta$  for various values of the rheological constant n [1) n = 2; 2) 1.25; 3) 1.15].

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VISCOUS EXPLOSION DURING THE NONISOTHERMAL MOTION OF AN INCOMPRESSIBLE LIQUID

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The hydrodynamic thermal explosion of an incompressible liquid moving under pressure in pipes was predicted theoretically in [1-3].

We present the hydraulic theory of a viscous explosion, which is caused by the nonlinear temperature dependence of viscosity.

Let us consider the laminar motion of an incompressible liquid in a circular pipe of radius R and length L. The pressure is  $p_1$  at the pipe inlet and  $p_2$  at the outlet. The temperature of the liquid at the inlet cross section is  $T_0$ , and a steady heat flux  $\lambda \partial T/\partial r = q_W < 0$  is specified at the pipe walls (heat is removed from the liquid). The physical quantities  $\lambda$ ,  $\rho$ , and  $C_p$  are assumed constant in the temperature range considered.

It is assumed that the Peclet number  $Pe = uR\rho C_p/\lambda \gg 1$ , so that axial heat conduction can be neglected in the heat-balance equation. We linearize the convective terms of this equation in the following way [4]:

**v** grad 
$$T \approx \frac{Q}{\pi R^2} \frac{\partial T}{\partial x}, \quad Q = -\pi \int_0^R \frac{du}{dr} r^2 dr.$$

Thus, we consider the equation

$$\frac{\lambda}{r}\frac{\partial}{\partial r}\left(r\frac{\partial T}{\partial r}\right) = \frac{\rho C_p Q}{\pi R^2}\frac{\partial T}{\partial x}.$$

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